PEARSON EDEXCEL INTERNATIONAL A LEVEL

MECHANICS 1

Student Book

Series Editors: Joe Skrakowski and Harry Smith

Authors: Greg Attwood, Jack Barraclough, Ian Bettison, Linnet Bruce, Alan Clegg, Gill Dyer, Jane Dyer, Keith Gallick, Susan Hooker, Michael Jennings, Mohammed Ladak, Jean Littlewood, Alistair Macpherson, Bronwen Moran, James Nicholson, Su Nicholson, Diane Oliver, Laurence Pateman, Keith Pledger, Joe Skrakowsi, Harry Smith, Geoff Staley, Robert Ward-Penny, Jack Williams, Dave Wilkins

Published by Pearson Education Limited, 80 Strand, London, WC2R 0RL.

www.pearsonglobalschools.com

Copies of official specifications for all Pearson qualifications may be found on the website: https://qualifications.pearson.com

Text © Pearson Education Limited 2018
Edited by Eric Pradel
Designed by © Pearson Education Limited 2018
Typeset by © Tech-Set Ltd, Gateshead, UK
Original illustrations © Pearson Education Limited 2018
Illustrated by © Tech-Set Ltd, Gateshead, UK
Cover design by © Pearson Education Limited 2018

The rights of Greg Attwood, Jack Barraclough, Ian Bettison, Linnet Bruce, Alan Clegg, Gill Dyer, Jane Dyer, Keith Gallick, Susan Hooker, Michael Jennings, Mohammed Ladak, Jean Littlewood, Alistair Macpherson, Bronwen Moran, James Nicholson, Su Nicholson, Diane Oliver, Laurence Pateman, Keith Pledger, Joe Skrakowsi, Harry Smith, Geoff Staley, Robert Ward-Penny, Jack Williams and Dave Wilkins to be identified as the authors of this work have been asserted by them in accordance with the Copyright, Designs and Patents Act 1988.

First published 2018

21 20 19 18 10 9 8 7 6 5 4 3 2 1

British Library Cataloguing in Publication Data A catalogue record for this book is available from the British Library

ISBN 978 1 292 24467 9

Copyright notice

All rights reserved. No part of this publication may be reproduced in any form or by any means (including photocopying or storing it in any medium by electronic means and whether or not transiently or incidentally to some other use of this publication) without the written permission of the copyright owner, except in accordance with the provisions of the Copyright, Designs and Patents Act 1988 or under the terms of a licence issued by the Copyright Licensing Agency, Barnard's Inn, 86 Fetter Lane, London, EC4A 1EN (www.cla.co.uk). Applications for the copyright owner's written permission should be addressed to the publisher.

Printed by Neografia in Slovakia

Picture Credits

The authors and publisher would like to thank the following individuals and organisations for permission to reproduce photographs:

(Key: b-bottom; c-centre; l-left; r-right; t-top)

Fotolia.com: Arousa 54; Getty Images: Jeff Schultz 39; Shutterstock.com: Algonga 7, Carlos Castilla 101, Carlos. E. Santa Maria 1, Joggie Botma 7, Lane V. Erickson 84, mbolina 112, Sinesp 10, 123RF.com: dmitrimaruta 129

Cover images: Front: Getty Images: Werner Van Steen Inside front cover: Shutterstock.com: Dmitry Lobanov

All other images © Pearson Education All artwork © Pearson Education

Endorsement Statement

In order to ensure that this resource offers high-quality support for the associated Pearson qualification, it has been through a review process by the awarding body. This process confirms that this resource fully covers the teaching and learning content of the specification or part of a specification at which it is aimed. It also confirms that it demonstrates an appropriate balance between the development of subject skills, knowledge and understanding, in addition to preparation for assessment.

Endorsement does not cover any guidance on assessment activities or processes (e.g. practice questions or advice on how to answer assessment questions) included in the resource, nor does it prescribe any particular approach to the teaching or delivery of a related course.

While the publishers have made every attempt to ensure that advice on the qualification and its assessment is accurate, the official specification and associated assessment guidance materials are the only authoritative source of information and should always be referred to for definitive guidance.

Pearson examiners have not contributed to any sections in this resource relevant to examination papers for which they have responsibility.

Examiners will not use endorsed resources as a source of material for any assessment set by Pearson. Endorsement of a resource does not mean that the resource is required to achieve this Pearson qualification, nor does it mean that it is the only suitable material available to support the qualification, and any resource lists produced by the awarding body shall include this and other appropriate resources.

COURSE STRUCTURE	iv
ABOUT THIS BOOK	vi
QUALIFICATION AND ASSESSMENT OVERVIEW	viii
EXTRA ONLINE CONTENT	X
1 MATHEMATICAL MODELS IN MECHANICS	1
2 CONSTANT ACCELERATION	10
3 VECTORS IN MECHANICS	39
4 DYNAMICS OF A PARTICLE MOVING IN A STRAIGHT LINE	54
REVIEW EXERCISE 1	7 9
5 FORCES AND FRICTION	84
6 MOMENTUM AND IMPULSE	101
7 STATICS OF A PARTICLE	112
8 MOMENTS	129
REVIEW EXERCISE 2	146
EXAM PRACTICE	150
GLOSSARY	153
ANSWERS	155
INDEX	166

CHAPTER 1 MATHEMATICAL		CHAPTER 4 DYNAMICS OF	
MODELS IN MECHANICS	1	A PARTICLE MOVING IN A	
1.1 CONSTRUCTING A MODEL	2	STRAIGHT LINE	54
1.2 MODELLING ASSUMPTIONS	4	4.1 FORCE DIAGRAMS	55
1.3 QUANTITIES AND UNITS	6	4.2 FORCES AS VECTORS	58
CHAPTER REVIEW 1	8	4.3 FORCES AND ACCELERATION	60
		4.4 MOTION IN TWO DIMENSIONS	64
CHAPTER 2 CONSTANT		4.5 CONNECTED PARTICLES	67
ACCELERATION	10	4.6 PULLEYS	71
2.1 DISPLACEMENT-TIME GRAPHS	11	CHAPTER REVIEW 4	75
2.2 VELOCITY-TIME GRAPHS	13		
2.3 ACCELERATION-TIME GRAPHS	17	REVIEW EXERCISE 1	79
2.4 CONSTANT ACCELERATION			
FORMULAE 1	19	CHAPTER 5 FORCES AND	
2.5 CONSTANT ACCELERATION		FRICTION	84
FORMULAE 2	24	5.1 RESOLVING FORCES	85
2.6 VERTICAL MOTION UNDER GRAVITY	29	5.2 INCLINED PLANES	90
CHAPTER REVIEW 2	35	5.3 FRICTION	94
		CHAPTER REVIEW 5	99
CHAPTER 3 VECTORS IN			
MECHANICS	39	CHAPTER 6 MOMENTUM AND	
3.1 WORKING WITH VECTORS	40	IMPULSE	101
3.2 SOLVING PROBLEMS WITH		6.1 MOMENTUM IN ONE DIMENSION	102
VECTORS WRITTEN USING	40	6.2 CONSERVATION OF MOMENTUM	104
I AND J NOTATION	42	CHAPTER REVIEW 6	104
3.3 THE VELOCITY OF A PARTICLE	45	CHAPTER REVIEW 0	109
AS A VECTOR	45		
3.4 SOLVING PROBLEMS INVOLVING VELOCITY AND TIME USING			
VECTORS	46		
CHAPTER REVIEW 3	50		

CHAPTER 7 STATICS OF A	
PARTICLE	112
7.1 STATIC PARTICLES	113
7.2 MODELLING WITH STATICS	117
7.3 FRICTION AND STATIC PARTICLES	121
CHAPTER REVIEW 7	126
CHAPTER 8 MOMENTS	129
8.1 MOMENTS	130
8.2 RESULTANT MOMENTS	132
8.3 EQUILIBRIUM	133
8.4 CENTRES OF MASS	136
8.5 TILTING	139
CHAPTER REVIEW 8	141
REVIEW EXERCISE 2	146
EXAM PRACTICE	150
GLOSSARY	153
ANSWERS	155
INDEX	166

ABOUT THIS BOOK

The following three overarching themes have been fully integrated throughout the Pearson Edexcel International Advanced Level in Mathematics series, so they can be applied alongside your learning and practice.

1. Mathematical argument, language and proof

- · Rigorous and consistent approach throughout
- Notation boxes explain key mathematical language and symbols
- · Opportunities to critique arguments and justify methods

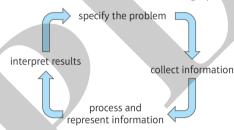
2. Mathematical problem-solving

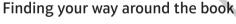
- Hundreds of problem-solving questions, fully integrated into the main exercises
- Problem-solving boxes provide tips and strategies
- Structured and unstructured questions to build confidence
- · Challenge questions provide extra stretch

3. Mathematical modelling

- Dedicated modelling sections in relevant topics provide plenty of practice where you need it
- Examples and exercises include qualitative questions that allow you to interpret answers in the context of the model

The Mathematical Problem-Solving Cycle





Each chapter starts with a list of Learning objectives

Learning objectives

Learning objectives

Learning objectives

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

Anter completing this Chapter you found the able to:

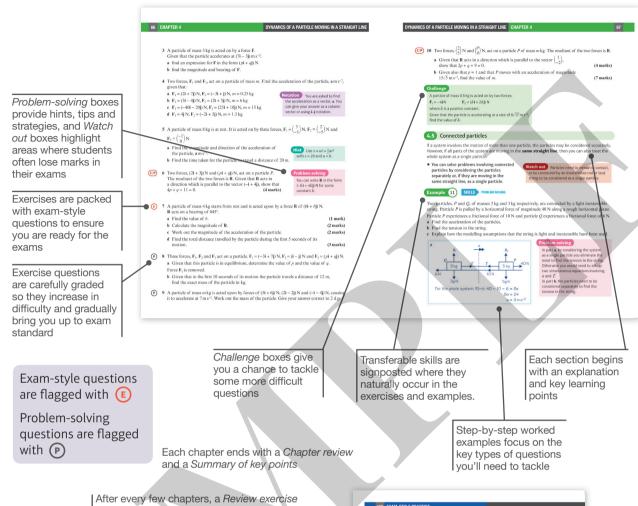
Anter completing this Chapter you found the able to:

Anter Chapter you are ready to start the chapter of the able to complete you are ready to start the chapter of the able to the able to the your anners correct to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the length of the hypotenuse and the later of the 12 seconds, the driver basks, caping the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the control to 1 d.p. = laternational CCS Mathamatics (and the Newton's Language trangle to the laternation o

Access an online digital edition using the code at the front of the book.



The real world applications of the maths you are about to learn are highlighted at the start of the chapter

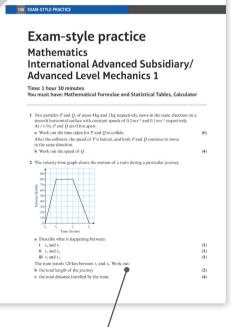


REVIEW DEFINISE

1 The figure shows the velocity time graph of a cyclest moving on a fringle mod over a 7 a period. The sections of the graph from 1 = 0 to 1 = 5/10 and from 1 = 3 to 1 = 7/10 at straight for 1 = 0 to 1 = 5/10 and from 1 = 3 to 1 = 7/10 at straight for 1 = 0 to 1 = 5/10 and from 1 = 3 to 1 = 7/10 at straight for 1 = 0 to 1 = 5/10 and from 1 = 3 to 1 = 7/10 at straight for 1 = 0 to 1 = 5/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight for 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 0 to 1 = 7/10 at straight from 2 to 1 = 7/10 at

helps you consolidate your learning with

lots of exam-style questions



A full practice paper at the back of the book helps you prepare for the real thing

QUALIFICATION AND ASSESSMENT OVERVIEW

Qualification and content overview

Mechanics 1 (M1) is an **optional** unit in the following qualifications:

International Advanced Subsidiary in Mathematics

International Advanced Subsidiary in Further Mathematics

International Advanced Level in Mathematics

International Advanced Level in Further Mathematics

Assessment overview

The following table gives an overview of the assessment for this unit.

We recommend that you study this information closely to help ensure that you are fully prepared for this course and know exactly what to expect in the assessment.

Unit	Percentage	Mark	Time	Availability
M1: Mechanics 1	33 ¹ / ₃ % of IAS	75	1 hour 30 mins	January, June and October
Paper code WME01/01	$16\frac{2}{3}$ % of IAL			First assessment June 2019

IAS – International Advanced Subsidiary, IAL – International Advanced A Level

Assess	ment objectives and weightings	Minimum weighting in IAS and IAL
A01	Recall, select and use their knowledge of mathematical facts, concepts and techniques in a variety of contexts.	30%
AO2	Construct rigorous mathematical arguments and proofs through use of precise statements, logical deduction and inference and by the manipulation of mathematical expressions, including the construction of extended arguments for handling substantial problems presented in unstructured form.	30%
AO3	Recall, select and use their knowledge of standard mathematical models to represent situations in the real world; recognise and understand given representations involving standard models; present and interpret results from such models in terms of the original situation, including discussion of the assumptions made and refinement of such models.	10%
A04	Comprehend translations of common realistic contexts into mathematics; use the results of calculations to make predictions, or comment on the context; and, where appropriate, read critically and comprehend longer mathematical arguments or examples of applications.	5%
AO5	Use contemporary calculator technology and other permitted resources (such as formulae booklets or statistical tables) accurately and efficiently; understand when not to use such technology, and its limitations. Give answers to appropriate accuracy.	5%

Relationship of assessment objectives to units

	Assessment objective				
M1	AO1	AO2	AO3	A04	AO5
Marks out of 75	20–25	20–25	15–20	6–11	4–9
%	$26\frac{2}{3} - 33\frac{1}{3}$	$26\frac{2}{3} - 33\frac{1}{3}$	20-26 ² / ₃	$8-14\frac{2}{3}$	5 ¹ / ₃ -12

Calculators

Students may use a calculator in assessments for these qualifications. Centres are responsible for making sure that calculators used by their students meet the requirements given in the table below.

Students are expected to have available a calculator with at least the following keys: +, -, ×, \div , π , x^2 , \sqrt{x} , $\frac{1}{x}$, x^y , $\ln x$, e^x , x!, sine, cosine and tangent and their inverses in degrees and decimals of a degree, and in radians; memory.

Prohibitions

Calculators with any of the following facilities are prohibited in all examinations:

- databanks
- retrieval of text or formulae
- built-in symbolic algebra manipulations
- symbolic differentiation and/or integration
- language translators
- communication with other machines or the internet



Extra online content

Whenever you see an Online box, it means that there is extra online content available to support you.



SolutionBank

SolutionBank provides a full worked solution for every question in the book.

Download all the solutions as a PDF or quickly find the solution you need online.

Use of technology

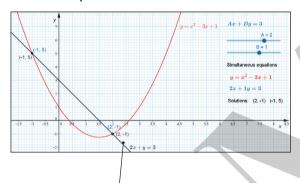
Explore topics in more detail, visualise problems and consolidate your understanding. Use pre-made GeoGebra activities or Casio resources for a graphic calculator.

Online Find the point of intersection graphically using technology.



Ge&Gebra

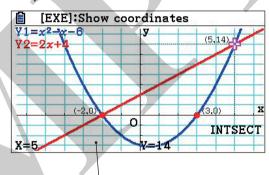
GeoGebra-powered interactives



Interact with the maths you are learning using GeoGebra's easy-to-use tools

CASIO

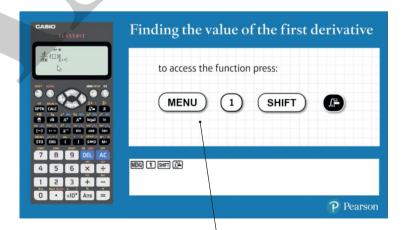
Graphic calculator interactives



Explore the maths you are learning and gain confidence in using a graphic calculator

Calculator tutorials

Our helpful video tutorials will guide you through how to use your calculator in the exams. They cover both Casio's scientific and colour graphic calculators.



Online Work out each coefficient quickly using the nC_r and power functions on your calculator.

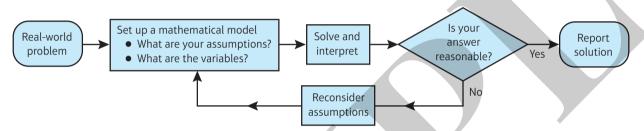
Step-by-step guide with audio instructions on exactly which buttons to press and what should appear on your calculator's screen

Constructing a model

Mechanics deals with motion and the action of forces on objects. Mathematical models can be constructed to simulate real-life situations (i.e. using models to create conditions that exist in real life, in order to study those conditions). However, in many cases it is necessary to simplify a problem by making one or more assumptions. This allows you to describe the problem using equations or graphs in order to solve it.

The solution to a mathematical model needs to be interpreted in the context of the original problem. It is possible that your model may need to be refined (improved with small changes) and your assumptions reconsidered.

This flow chart summarises the mathematical modelling process:



Example SKILLS PROBLEM-SOLVING

The motion of a basketball as it leaves a player's hand and passes through the net can be modelled using the equation $h = 2 + 1.1x - 0.1x^2$, where h m is the height of the basketball above the ground and x m is the horizontal distance travelled.

- **a** Find the height of the basketball:
 - i when it is released
 - ii at a horizontal distance of 0.5 m.
- **b** Use the model to predict the height of the basketball when it is at a horizontal distance of 15 m from the player.
- c Comment on the validity of this prediction.

a i
$$x = 0$$
: $h = 2 + 0 - 0$
Height = 2 m
ii $x = 0.5$: $h = 2 + 1.1 \times 0.5 - 0.1 \times (0.5)^2$
Height = 2.525 m
b $x = 15$: $h = 2 + 1.1 \times 15 - 0.1 \times (15)^2$
Height = -4 m
c Height cannot be **negative** so the model is not valid when $x = 15$ m.

When the basketball is released at the start of the motion x = 0. Substitute x = 0 into the equation for *h*.

Substitute x = 0.5 into the equation for h.

Substitute x = 15 into the equation for h.

h represents the height of the basketball above the ground, so it is only valid if $h \ge 0$.



- 1 The motion of a golf ball after it is struck by a golfer can be modelled using the equation $h = 0.36x 0.003x^2$, where h m is the height of the golf ball above the ground and x m is the horizontal distance travelled.
 - a Find the height of the golf ball when it is:
 - i struck
- ii at a horizontal distance of 100 m.
- **b** Use the model to predict the height of the golf ball when it is at a horizontal distance of 200 m from the golfer.
- **c** Comment on the validity of this prediction.
- 2 A stone is thrown into the sea from the top of a cliff. The height of the stone above sea level, h m at time t s after it is thrown can be modelled by the equation $h = -5t^2 + 15t + 90$.
 - a Write down the height of the cliff above sea level.
 - **b** Find the height of the stone:
 - **i** when t = 3
- ii when t = 5.
- **c** Use the model to predict the height of the stone after 20 seconds.
- **d** Comment on the validity of this prediction.
- P 3 The motion of a basketball as it leaves a player's hand and passes through the net is modelled using the equation $h = 2 + 1.1x 0.1x^2$, where h m is the height of the basketball above the ground and x m is the horizontal distance travelled.
 - a Find the two values of x for which the basketball is exactly 4 m above the ground.

This model is valid for $0 \le x \le k$, where k m is the horizontal distance of the net from the player.

- **b** Given that the height of the net is $3 \, \text{m}$, find the value of k.
- **c** Explain why the model is not valid for x > k.
- P 4 A car accelerates from rest to $60 \,\mathrm{km} \,\mathrm{h}^{-1}$ in 10 seconds. A quadratic equation of the form $d = kt^2$ can be used to model the distance travelled, d metres in time t seconds.

Problem-solving

Use the information given to work out the value of k.

- **a** Given that when t = 1 second the distance travelled by the car is 13.2 metres, use the model to find the distance travelled when the car reaches 60 km h^{-1} .
- **b** Write down the range of values of t for which the model is valid.
- P 5 The model for the motion of a golf ball given in question 1 is valid only when h is positive. Find the range of values of x for which the model is valid.
- P 6 The model for the height of the stone above sea level given in question 2 is valid only from the time the stone is thrown until the time it enters the sea. Find the range of values of t for which the model is valid.

1.2 Modelling assumptions

Modelling assumptions can simplify a problem and allow you to analyse a real-life situation using known mathematical techniques. You need to understand the significance of different modelling assumptions and how they affect the calculations in a particular problem.

Watch out

Modelling assumptions can affect the validity of a model. For example, when modelling the landing of an aeroplane flight, it would not be appropriate to ignore the effects of wind and air resistance.

This table shows some common models and modelling assumptions that you need to know.

Model	Modelling assumptions
Particle – Dimensions of the object are negligible.	 mass of the object is concentrated at a single point rotational forces (i.e. moving around a central fixed point) and air resistance can be ignored
Rod – All dimensions but one are negligible, like a pole or a beam.	 mass is concentrated along a line no thickness rigid (does not bend or buckle)
Lamina – Object with area but negligible thickness, like a sheet of paper.	mass is distributed across a flat surface
Uniform body – Mass is distributed evenly.	mass of the object is concentrated at a single point at the geometric centre of the body – the centre of mass
Light object – Mass of the object is small compared to other masses, like a string or a pulley.	 treat object as having zero mass tension the same at both ends of a light string
Inextensible string – A string that does not stretch under load.	 acceleration is the same in objects connected by a taut inextensible string
Smooth surface – a surface on which it can be assumed there is no friction.	 assume that there is no friction between the surface and any object on it
Rough surface – a surface on which there is friction.	 objects in contact with the surface experience a frictional force if they are moving, or are acted on by a force
Wire – Rigid thin length of metal.	treated as one-dimensional
Smooth and light pulley – All pulleys you consider will be smooth and light.	pulley has no masstension is the same on either side of the pulley
Bead – Particle with a hole in it for threading on a wire or string (i.e. passing the wire or string through the hole).	 a smooth bead moves freely along a wire or string for a smooth bead, tension is the same on either side of the bead
Peg – A support from which a body can be suspended or rested.	dimensionless and fixedcan be rough or smooth as specified in the question
Air resistance – Resistance experienced as an object moves through the air.	usually modelled as being negligible
Gravity – Force of attraction between all objects. Acceleration due to gravity is denoted by g . $g = 9.8 \text{ m s}^{-2}$	 assume all objects with mass are attracted toward the Earth acceleration due to Earth's gravity is uniform (i.e. the same in all parts, at all times) and acts vertically downward g is constant and is taken as 9.8 m s⁻², unless otherwise stated in the question



A mass is attached to a length of string which is fixed to the ceiling.

The mass is drawn to one side with the string stretched tightly and allowed to swing.

State the effect of the following assumptions on any calculations made using this model.

- a The string is **light and inextensible** (unable to be stretched further).
- **b** The mass is modelled as a particle.
 - **a** Ignore the mass of the string and any stretching effect caused by the mass.
 - **b** Ignore the rotational effect of any external forces that are acting on it, and the effects of air resistance.

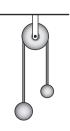


- 1 A football is kicked by the goalkeeper from one end of the football pitch.

 State the effect of the following assumptions on any calculations made using this model.
 - a The football is modelled as a particle.
 - **b** Air resistance is negligible.
- 2 An ice hockey puck is hit and slides across the ice.

State the effect of the following assumptions on any calculations made using this model.

- a The ice hockey puck is modelled as a particle.
- **b** The ice is smooth.
- 3 A parachutist wants to model her descent from an aeroplane to the ground. She models herself and her parachute as particles connected by a light inextensible string. Explain why this may not be a suitable modelling assumption for this situation.
- **4** A fishing rod manufacturer constructs a mathematical model to predict the behaviour of a particular fishing rod. The fishing rod is modelled as a light rod.
 - a Describe the effects of this modelling assumption.
 - **b** Comment on its validity in this situation.
- 5 Make a list of the assumptions you might make to create simple models of the following:
 - a the motion of a golf ball after it is hit
 - **b** the motion of a child on a sledge going down a snow-covered hill
- c the motion of two objects of different masses connected by a string that passes over a pulley
 - **d** the motion of a suitcase on wheels being pulled along a path by its handle.



1.3 Quantities and units

The International System of Units, (abbreviated SI from the French, Système international d'unités) is the modern form of the metric system. These **base SI units** are most commonly used in mechanics:

Quantity	Unit	Symbol
Mass	kilogram	kg
Length/displacement	metre	m
Time	second	S

Watch out

A common misunderstanding is that kilograms measure **weight**, not mass. However, **weight** is a **force** which is measured in **newtons** (**N**).

These **derived** units are compound units built from the base units:

Quantity Unit		Symbol
Speed/velocity	metres per second	m s ⁻¹
Acceleration	metres per second per second	m s ⁻²
Weight/force	newton	N (= kg m s ⁻²)

Example

3 SKILLS

REASONING/ARGUMENTATION

Write the following quantities in SI units.

a 4km

b 0.32 grams

 $c 5.1 \times 10^6 \,\mathrm{km}\,\mathrm{h}^{-1}$

a
$$4 \text{ km} = 4 \times 1000 = 4000 \text{ m}$$

b $0.32 \text{ g} = 0.32 \div 1000 = 3.2 \times 10^{-4} \text{ kg}$
c $5.1 \times 10^{6} \text{ km h}^{-1} = 5.1 \times 10^{6} \times 1000$
 $= 5.1 \times 10^{9} \text{ m h}^{-1}$
 $5.1 \times 10^{9} \div (60 \times 60) = 1.42 \times 10^{6} \text{ m s}^{-1}$

The SI unit of length is the metre; 1 km = 1000 m.

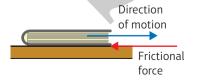
The SI unit of mass is the kg; 1 kg = 1000 g. The answer is given in standard form.

The SI unit of speed is $m s^{-1}$. Convert from $km h^{-1}$ to $m h^{-1}$ by multiplying by 1000.

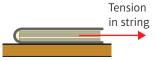
Convert from m h⁻¹ to m s⁻¹ by dividing by 60×60 . The answer is given in standard form to 3 s.f.

You will encounter a variety of forces in mechanics. These **force diagrams** show some of the most common forces.

- The weight (or gravitational force) of an object acts vertically downward.
- The **normal reaction** is the force which acts perpendicular (i.e. at a 90° angle to it) to a surface when an object is in contact with the surface. In this example the normal reaction is due to the weight of the book resting on the surface of the table.
- Friction is a force which opposes the motion between two rough surfaces.



 If an object is being pulled along by a string, the force acting on the object is called the **tension** in the string.



Force exerted on the table by the book.

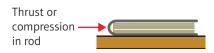
Both forces have the same magnitude.

Normal reaction exerted

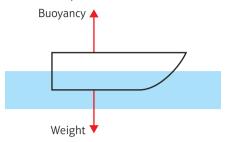
on the book (i.e. applied

to it) by the table.

 If an object is being pushed along using a light rod, the force acting on the object is called the **thrust** or **compression** in the rod.



Buoyancy is the upward force on a body that allows it to float or rise when submerged (i.e. underneath the surface) in a liquid. In this example buoyancy acts to keep the boat afloat in the water.





The force diagram shows an aircraft in flight. Write down the names of the four forces shown on the diagram.

Also known as 'lift', this is the upward force that keeps the aircraft up in the air.



Exercise

- 1 Convert to SI units:
 - a 65 km h⁻¹

- **b** $15 \,\mathrm{g} \,\mathrm{cm}^{-2}$
- **b** $15 \,\mathrm{g \, cm^{-2}}$ **e** $4.5 \times 10^{-2} \,\mathrm{g \, cm^{-3}}$ **d** $24 \, \text{g m}^{-3}$

• Air resistance opposes motion. In this example the weight of the parachutist acts vertically downward and the air resistance acts vertically upward.

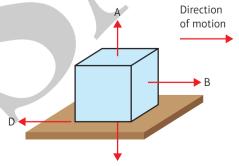


Also known as 'thrust', this is the force that propels the aircraft forward.

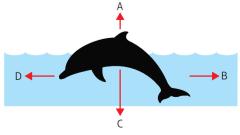
This is the gravitational force acting downward on the aircraft.

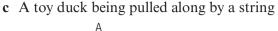
Also known as 'drag', this is the force that acts in the **opposite** direction to the forward thrust.

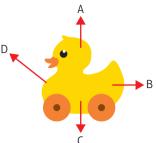
- c 30 cm per minute
- $f 6.3 \times 10^{-3} \,\mathrm{kg} \,\mathrm{cm}^{-2}$
- 2 Write down the names of the forces shown in each of these diagrams.
 - a A box being pushed along rough ground

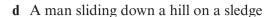


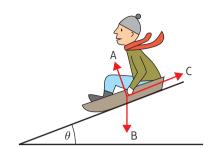
b A dolphin swimming through the water



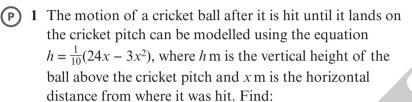








Chapter review



Hint The path of the cricket ball is modelled as a quadratic curve. Draw a sketch for the model and use the symmetry of the curve.

- a the vertical height of the ball when it is at a horizontal distance of 2 m from where it was hit
- **b** the two horizontal distances for which the height of the ball was 2.1 m.

Given that the model is valid from when the ball is hit to when it lands on the cricket pitch:

- **c** find the values of x for which the model is valid
- **d** work out the **maximum** height of the cricket ball.
- (P) 2 A diver dives from a diving board into a swimming pool with a depth of 4.5 m. The height of the diver above the water, h m, can be modelled using $h = 10 - 0.58x^2$ for $0 \le x \le 5$, where x m is the horizontal distance from the end of the diving board.
 - a Find the height of the diver when $x = 2 \,\mathrm{m}$.
 - **b** Find the horizontal distance from the end of the diving board to the point where the diver enters the water.

In this model the diver is modelled as a particle.

- c Describe the effects of this modelling assumption.
- **d** Comment on the validity of this modelling assumption for the motion of the diver after she enters the water.
- 3 Make a list of the assumptions you might make to create simple models of the following:
 - a the motion of a man skiing down a snow-covered slope
 - **b** the motion of a yo-yo on a string.

In each case, describe the effects of the modelling assumptions.

Uncorrected proof, all content subject to change at publisher discretion. Not for resale, circulation or distribution in whole or in part. ©Pearson 2019

- 4 Convert to SI units:
 - a 2.5 km per minute
- **b** $0.6 \,\mathrm{kg} \,\mathrm{cm}^{-2}$ **c** $1.2 \times 10^3 \,\mathrm{g} \,\mathrm{cm}^{-3}$
- 5 A man throws a bowling ball in a bowling alley.
 - a Make a list of the assumptions you might make to create a simple model of the motion of the bowling ball.
 - **b** Taking the direction in which the ball travels as the positive direction, state with a reason whether each of the following are likely to be positive or negative:
 - i the velocity
- ii the acceleration.

Summary of key points

- Mathematical models can be constructed to simulate real-life situations.
- Modelling assumptions can be used to simplify your calculations. 2
- The base SI units most commonly used in mechanics are:

Quantity	Unit	Symbol
Mass	kilogram	kg
Length/displacement	metre	m
Time	second	S

The derived SI units most commonly used in mechanics are:

Quantity	Unit	Symbol
Speed/velocity	metres per second	m s ⁻¹
Acceleration	metres per second per second	m s ⁻²
Weight/force	newton	N (= kg m s ⁻²)