

## Year 12 AS Maths

Lesson Group	Specification coverage	Lesson 1	Lesson 2	Lesson 3	Lesson 4	Lesson 5	Pre-Test	Post-Test
<b>A: Reinforcing Pre-requisites to Year 12</b>	2.1 – 2.5, 2.7	Index laws	Surds and rationalising denominators	Solving quadratics	Linear and non-linear simultaneous equations	Graphs of quadratic, cubic, quartic and reciprocal functions	<b>A</b>	<b>A</b>
<b>B: Algebraic methods</b>	1.1, 2.6 3.1, 3.2, 4.1	Equations of straight lines and circles	Dividing polynomials and the factor theorem	Algebraic fractions	The binomial expansion	Algebraic proof	<b>B</b>	<b>B</b>
<b>C: Trigonometric</b>	5.1, 5.3, 5.5, 5.7	The sine rule, cosine rule and area problems	Angles in all four quadrants	Trigonometric identities	Trigonometric equations	Equations and identities	<b>C</b>	<b>C</b>
<b>D: Calculus</b>	7.1-7.3, 8.1 – 8.3	Differentiation from 1 <sup>st</sup> principles	Gradients, tangents and normal	Stationary points	Indefinite integrals	Definite integrals	<b>D</b>	<b>D</b>
<b>E: Exponentials and logarithms</b>	6.1 – 6.7	Exponential modelling	Laws or logarithms	Solving equations using logarithms	Working with natural logarithms	Logarithms and non-linear data	<b>E</b>	<b>E</b>
<b>F: Statistic</b>	1.1, 2.3, 3.1, 4.1, 5.1, 5.2	Types of sampling	Standard deviation calculations	Mutually exclusive and independent events	The binomial distribution	Hypothesis testing	<b>F</b>	<b>F</b>
<b>G: Mechanics</b>	7.1, 7.2, 7.3, 7.4, 8.1- 8.4	Displacement-time and velocity-time graphs	Constant acceleration formulae	Forces and newtons laws	Motion in 2D	Variable acceleration	<b>G</b>	<b>G</b>

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<b>A: Trigonometry I</b>	5.1, 5.3, 5.4, 5.5	Fundamentals of sec, cosec, cot	Graphs of sec, cosec, cot	Solving equations with sec, cosec, cot	Trigonometric identities	Inverse trigonometric functions	<b>A</b>	<b>A</b>
<b>B: Trigonometry II</b>	5.6, 5.8, 5.9	Addition formulae	The double angle formulae	Solving trigonometric equations	Simplifying $a \sin x \pm b \cos x$	Modelling with trigonometric functions	<b>B</b>	<b>B</b>
<b>C: Parametric equations</b>	3.3, 3.4, 7.4, 7.5	Using trigonometric identities and curve sketching	Points of intersection	Modelling with parametric equations	Parametric differentiation	Parametric integration	<b>C</b>	<b>C</b>
<b>D: Differentiation</b>	7.1, 7.2, 7.3, 7.4, 7.5	Differentiating $\sin x$ , $\cos x$	Chain product and quotient rules	Differentiating trigonometric function	Implicit differentiation	Second derivatives and rates of change	<b>D</b>	<b>D</b>
<b>E: Integration I</b>	8.2, 8.3, 8.4,	Integrating standard functions	Integrating $f(ax + b)$	Using trigonometric identities	Integrating in the form $ab^x$	Reverse chain rule	<b>E</b>	<b>E</b>
<b>F: Integration II</b>	8.5 – 8.8	Integration by substitution	Integration by parts	Integration by substitution	Partial fractions	Solving differential equations	<b>F</b>	<b>F</b>
<b>G: Statistics</b>	3.2, 3.3, 4.2, 4.3, 5.1, 5.3,	Regression and hypothesis tests	5	Normal and inverse normal distribution probabilities	The standard normal distribution	Hypothesis testing with the normal distribution	<b>G</b>	<b>G</b>
<b>H: Mechanics</b>	8.1 – 8.6, 9.1	Forces and friction	Projectiles	Dynamics and inclined planes	Vector method in mechanics	Statics of rigid bodies	<b>H</b>	<b>H</b>