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| **Applying and Visualizing Transformations on a Grid** |
| Identifies and describes transformations on a grid.“Shape A to Shape D is a translation. Shape A is reflected in the horizontal line halfway between Shapes A and C to get Shape C. Shape A is rotated 90° clockwise about point R to get Shape B.” | Describes and performs single transformations on a grid. “I translated Shape A left 7 squares and down 2 squares to Image D.” | Describes and performs combinations of transformations.“I used a combination of transformations. I translated the Shape right 4 squares, down 2 squares to Image 1; I reflected Image 1 in the line of reflection shown to get Image 2; I rotated Image 2 90° clockwise about point P to get Image 3.” | Visualizes, describes, and flexibly performs combinations of transformations.“I visualized the transformations and predicted where the images would be. I performed the transformations to check. I rotated the shape 180° about point P to get Image 1; then translated Image 1 right 4 squares to get Image 2; then reflected Image 2 in the common side to get Image 3. My predictions were correct.” |
| **Observations/Documentation** |
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| **Locating and Mapping Shapes in 1st Quadrant of the Cartesian Plane** |
| Describes the location of 2-D shape/objects on the grid.“The treasure chest is located at (6,3).” | Describes translations of points by describing distance, direction, and coordinates.“I plotted the point C(5, 7), then translated it right 5 squares to C’(10, 5). The *x*-coordinate increased by 5.” | Plots and locates points on a grid using various scales and labels the coordinates.“To plot each point, I counted by 5s along each axis and labelled the coordinates: W(0,30), N(15,0), V(35,20), U(40,25), M(45,5).” |
| **Observations/Documentation** |
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| **Locating and Mapping Shapes in 1st Quadrant of the Cartesian Plane (cont’d)** |
| Translates or reflects shapes and labels coordinates of the image. “I translated the quadrilateral right 4 squares, then down 5 squares. The *x*-coordinate of each vertex of the image increased by 4 and each *y*-coordinate decreased by 5.” | Analyzes and locates the vertices of 2-D shapes before and after rotations.“I rotated the shape 180° about P(8, 10). I chose point P because it is on the line of symmetry of the trapezoid, so when I rotate it 180°, the image is also a reflection.” | Visualizes and predicts the location of 2-D shapes after transformations using various scales. “I visualized and predicted the location of the image after different transformations and identified the coordinates. Image 1 is a rotation 90° clockwise, and Image 2 is a translation right 5 squares, down 9 squares.” |
| **Observations/Documentation** |
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